

RING ASTROMETRIC FIELD TELESCOPE

Deborah Busonero on behalf of the collaboration
INAF-OATo

A future space mission with very high precision astrometry
Paris, 11-13 September 2024

PRESENTATION LAYOUT

- Introduction
- Scientific scenario
- Rafter description
- Technological challenges
- Conclusions

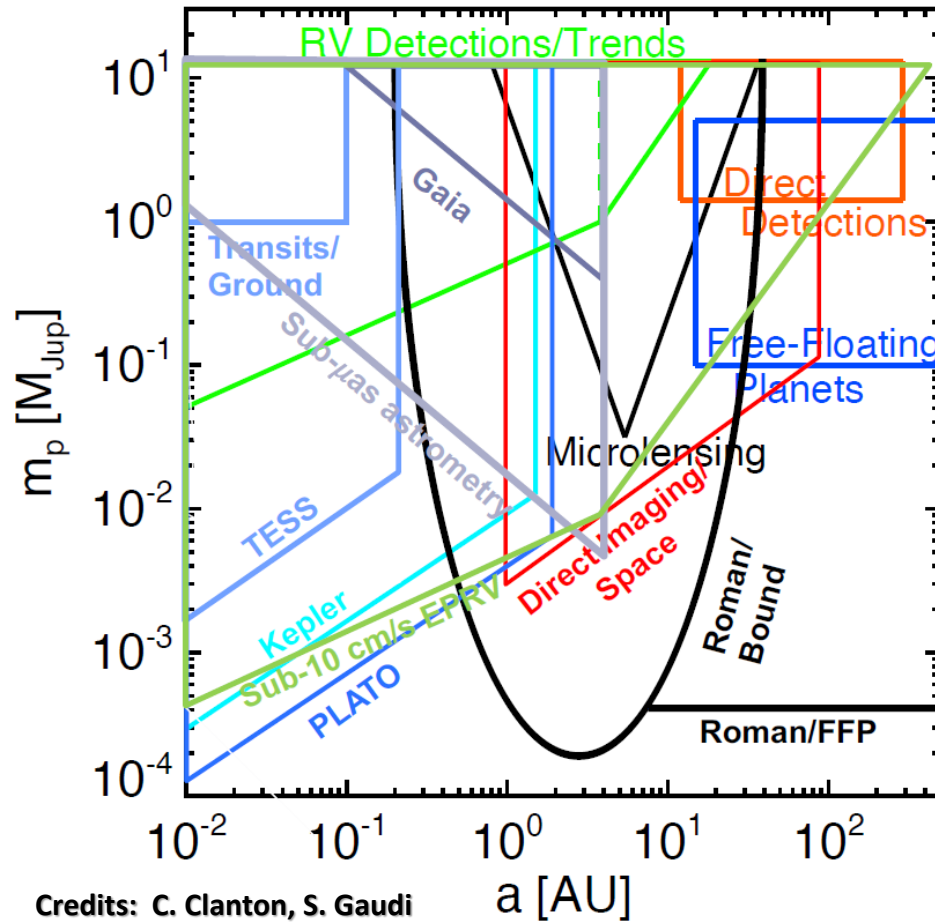
INTRODUCTION

- ❑ This talk is focused on a dedicated sub- μ s astrometry instrument configuration called RAFTER.
- ❑ Local-differential astrometry.
- ❑ Innovative concept of on-axis TMA which reduces the complications of the classic TMA while maintaining its large corrected field advantage.
- ❑ Innovative technique for PSF centering at the 1/5900 pixel level to reach sub- μ s astrometry.

Riva, A., et. al., SPIE 2020;

Gai M., et. al., PASP 2022

MAIN SCIENTIFIC TARGET



- Sub- μ as astrometry from space is the only technique capable of performing a complete census of Earth-mass planets in the Habitable Zones (HZs) of F-G-K-type stars within 20 pc from the Sun without selection effects. Typical $V=8-12$ mag
 - ultimate target provider for future space missions such as HWO or LIFE aimed at the spectroscopic detection of bio signatures in the atmospheres of temperate telluric planets

1 Earth mass planet in the HZ($a=1$ AU) of a solar-mass star at 10 pc the astrometric signal is $\approx 0.3 \mu$ as

BUT NOT ONLY....

a) shape and dynamics of Dark Matter halos in selected collective systems (dwarf spheroidal galaxies, samples of Milky Way halo stars and hyper-velocity stars);

b) calibration of the cosmic distance ladder on distant pulsating variables (Cepheids, RR Lyrae, Miras) well beyond the limits of Gaia (i.e. at the μas level at $G \simeq 15$ mag); (changing in time exposition)

c) high-accuracy masses and orbits of X-ray binaries hosting neutron stars and black holes (visible counterpart);

d) identification of candidate systems for future gravitational wave observations and measurements of the stochastic background of gravitational waves (in sliding modified configuration Gai this workshop).

RING ASTROMETRIC FIELD TELESCOPE

- μ as astrometry compatible with 1m-class telescopes
- Local astrometry
- Innovative TMA design



SCENARIO

- Large corrected field requires TMA
- Traditional TMA's require off axis configurations (e.g. JWST, Gaia, ...)
- TMA presents lot of issues in alignment procedures and alignment maintenance (metrology issues)-> demanding optomechanics -> low TRL
- IF we accept the central field (around optical axis) obscuration we can design an ON-AXIS TMA -> a lot easier to align (e.g. like traditional telescopes design) -> more relaxed requirements



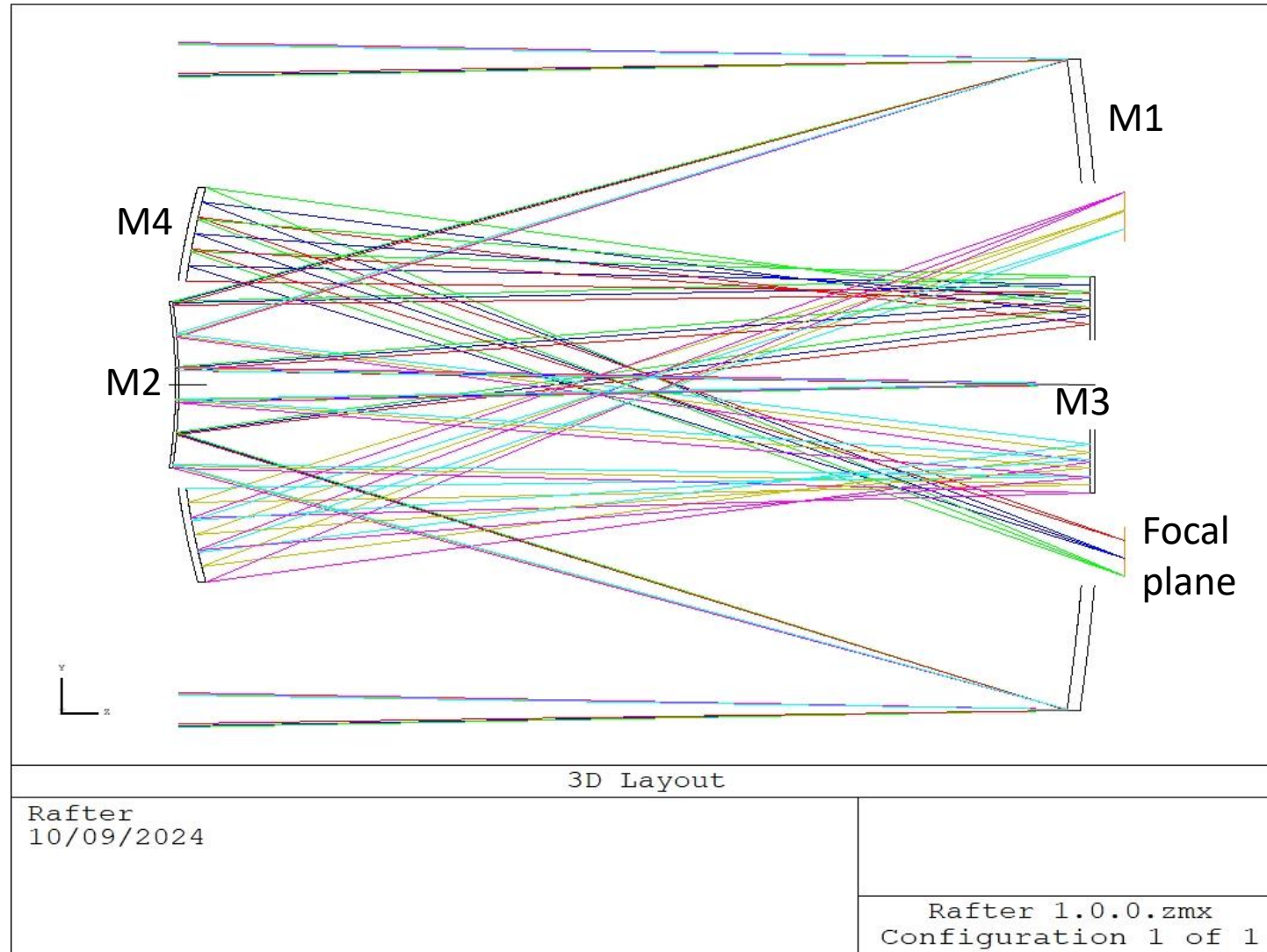
IDEA

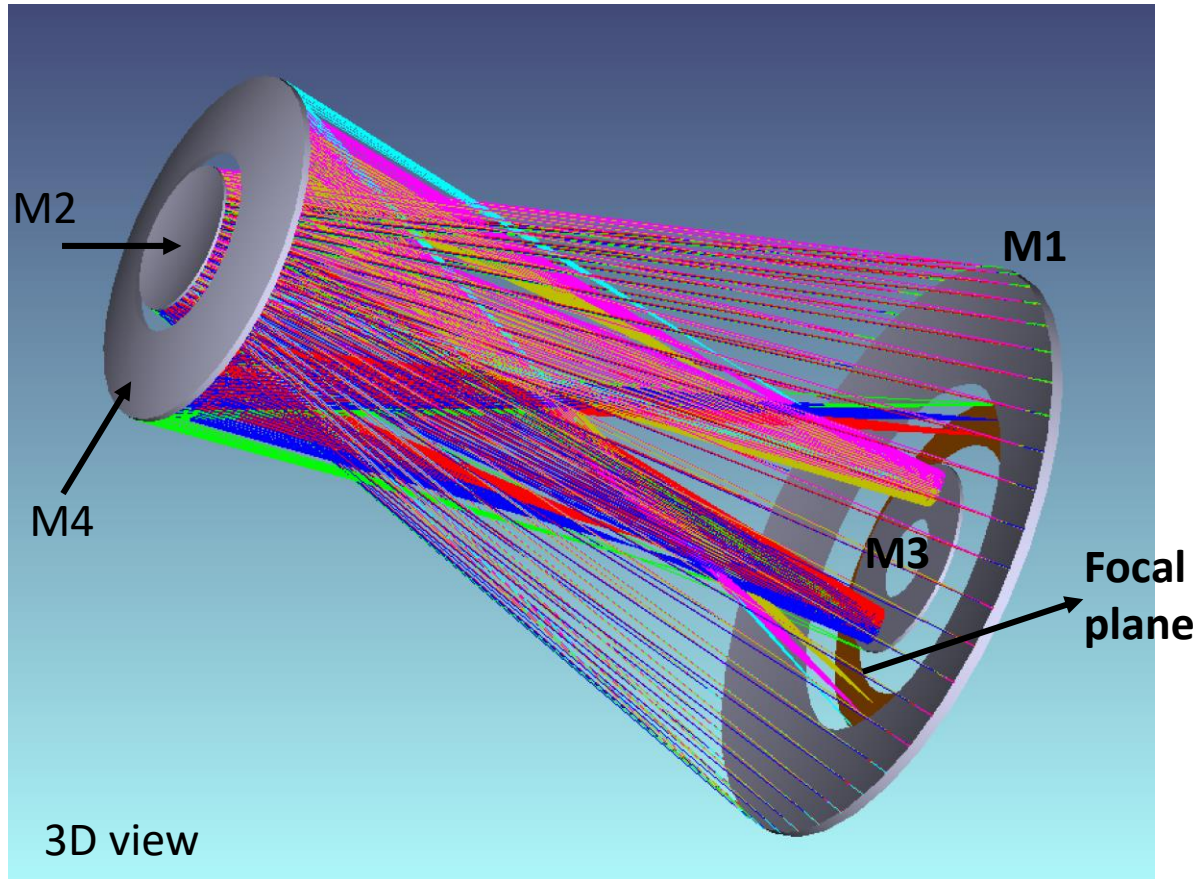
- We propose an on-axis telescope materialized by means of annular mirrors (rings)
- Annular focal plane -> ring of detectors
- Analogies with AGP design [Riva, A., et al, SPIE 2016]



OPTICAL DESIGN: LAYOUT

Design & analysis: Zemax
OpticStudio





Compact structure \longrightarrow whole envelope: <2 m

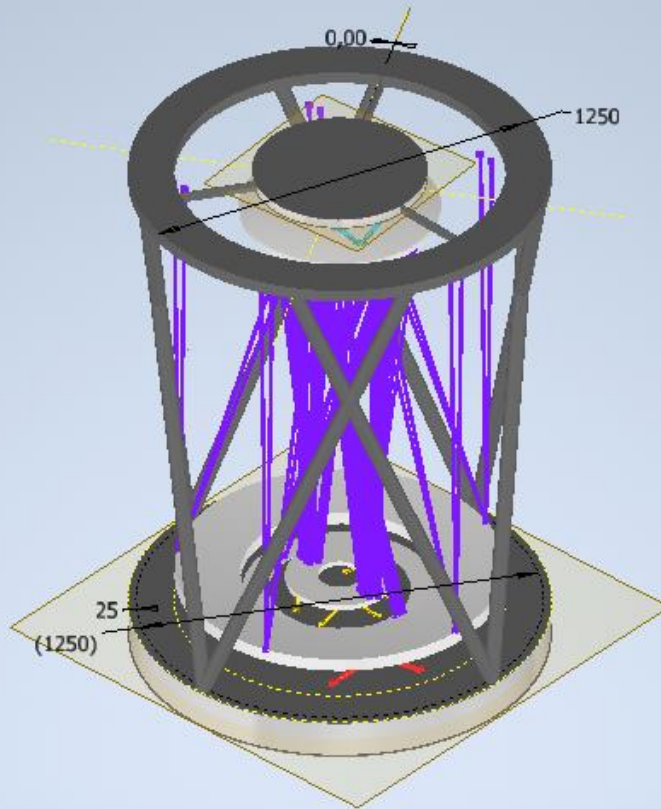
Simmetry

Simplified alignment of M1/M3-M2/M4 zones

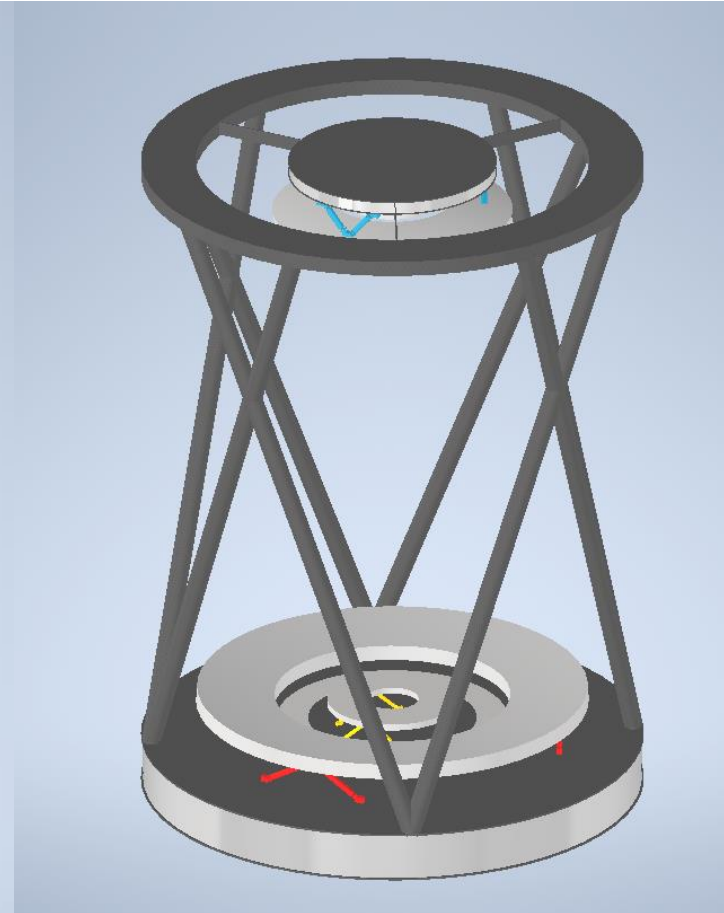
- ✓ The telescope is naturally split into two smaller optomechanical units, facing each other;
- ✓ this arrangement ensures the mutual placement stability of the nearby mirrors, thus relaxing the overall number of degrees of freedom and complexity;
- ✓ each mirror pair is also subject to a common local thermal environment, including its thermo-elastic perturbations



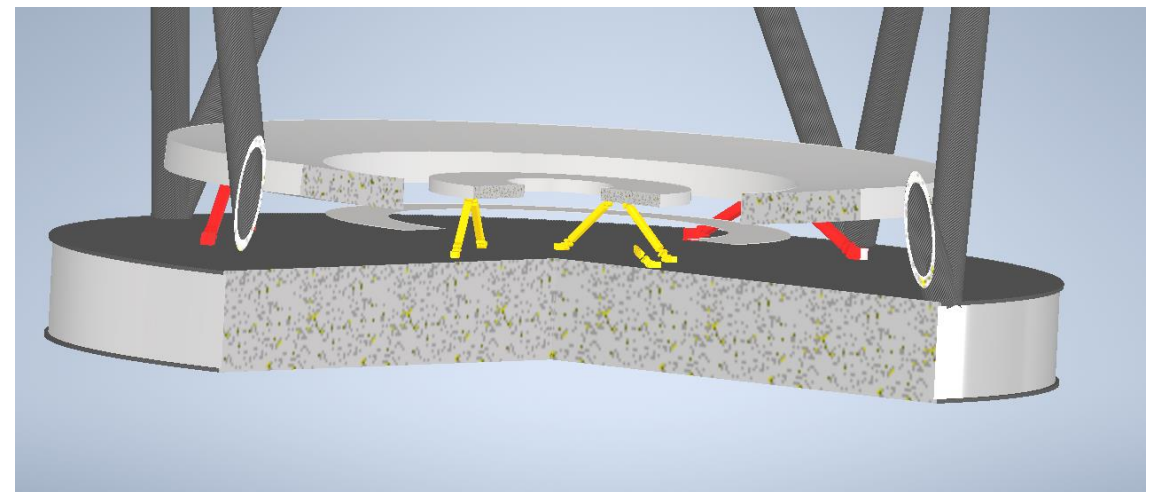
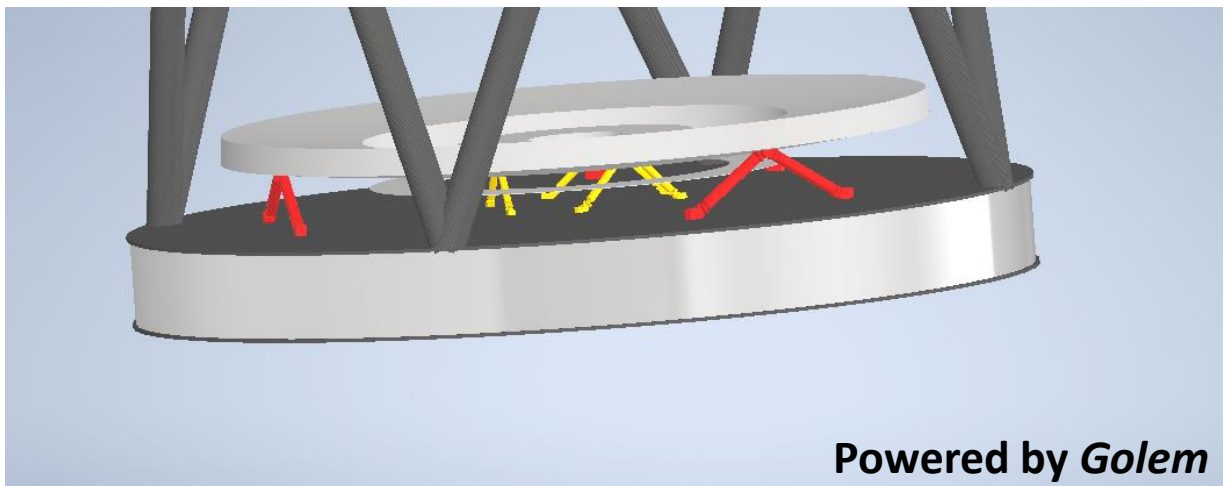
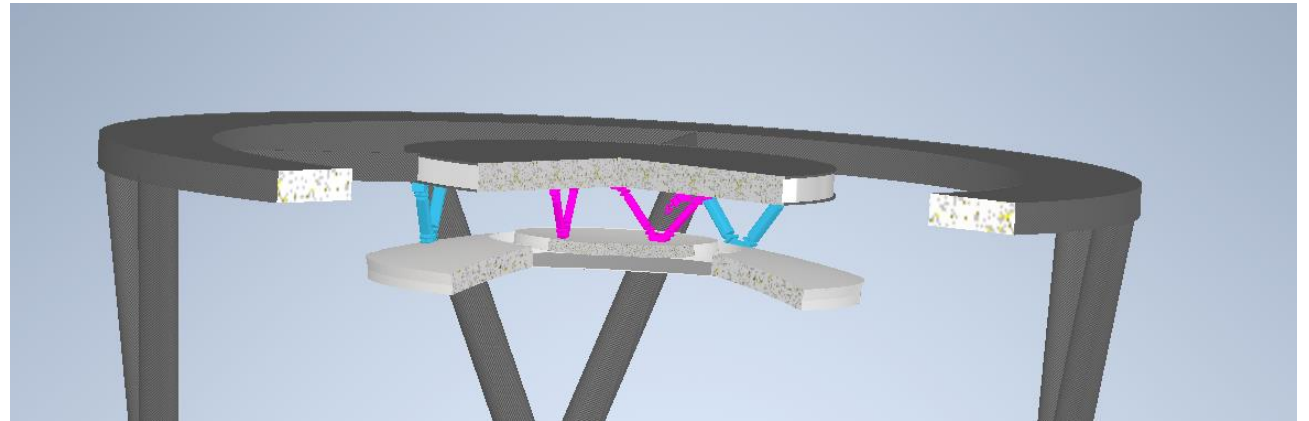
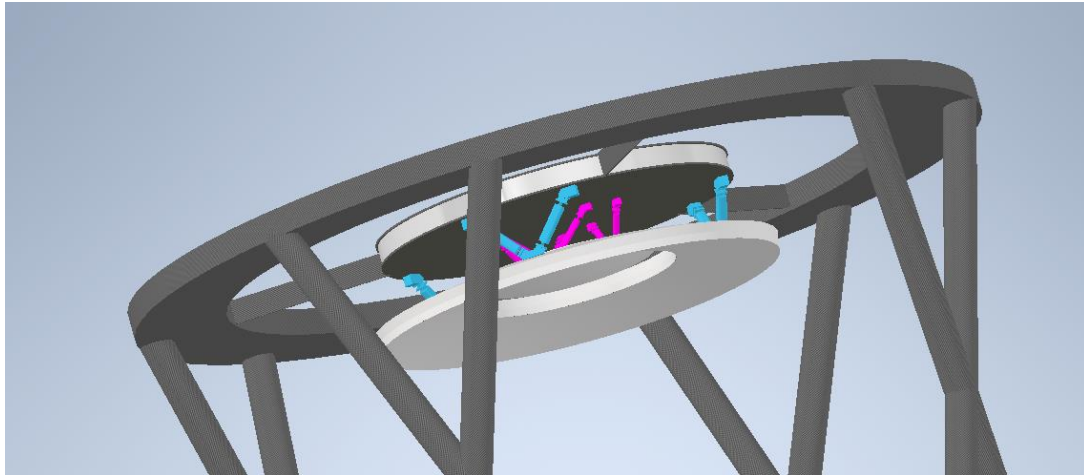
OPTO-MECHANICAL CONCEPT



Powered by *Golem*



OPTO-MECHANICAL CONCEPT - DETAILS



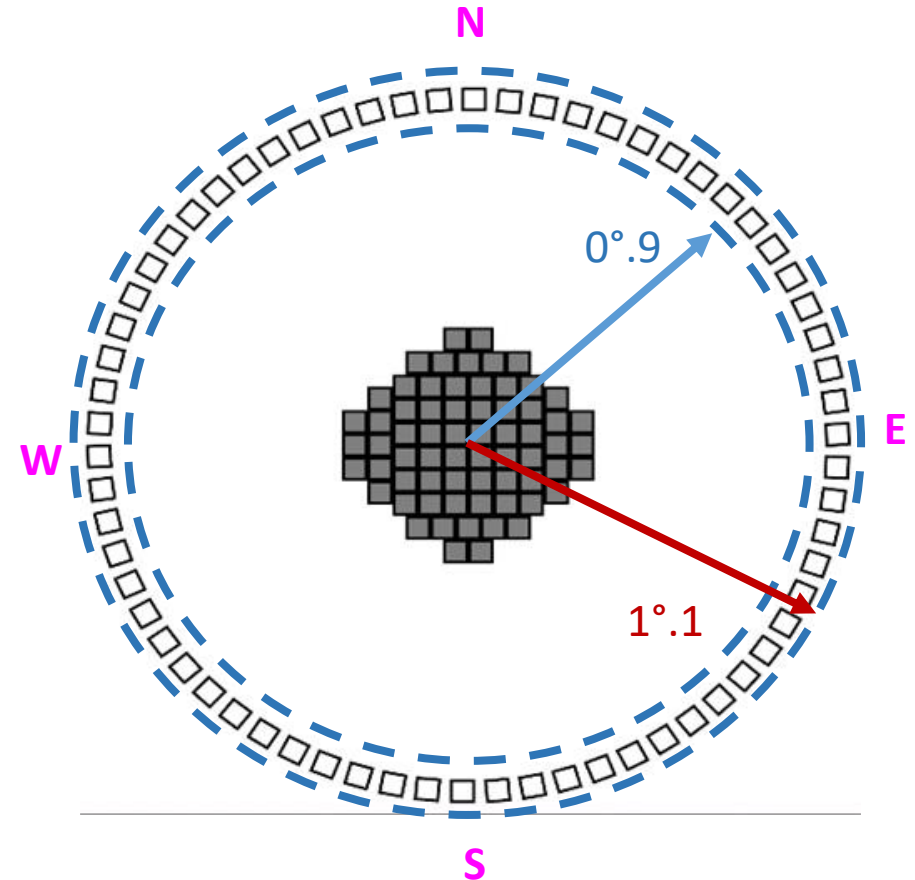
TELESCOPE PARAMETERS

- Diameter: 1 m
- Length: 1.4 m
- EFL: 15 m
- f-number: 15
- Diffraction limited
- Platescale 50 mas/pixel



Compatible with 4-5 μm pixel
CMOS detectors

- FOV: $1^\circ \pm 10'$

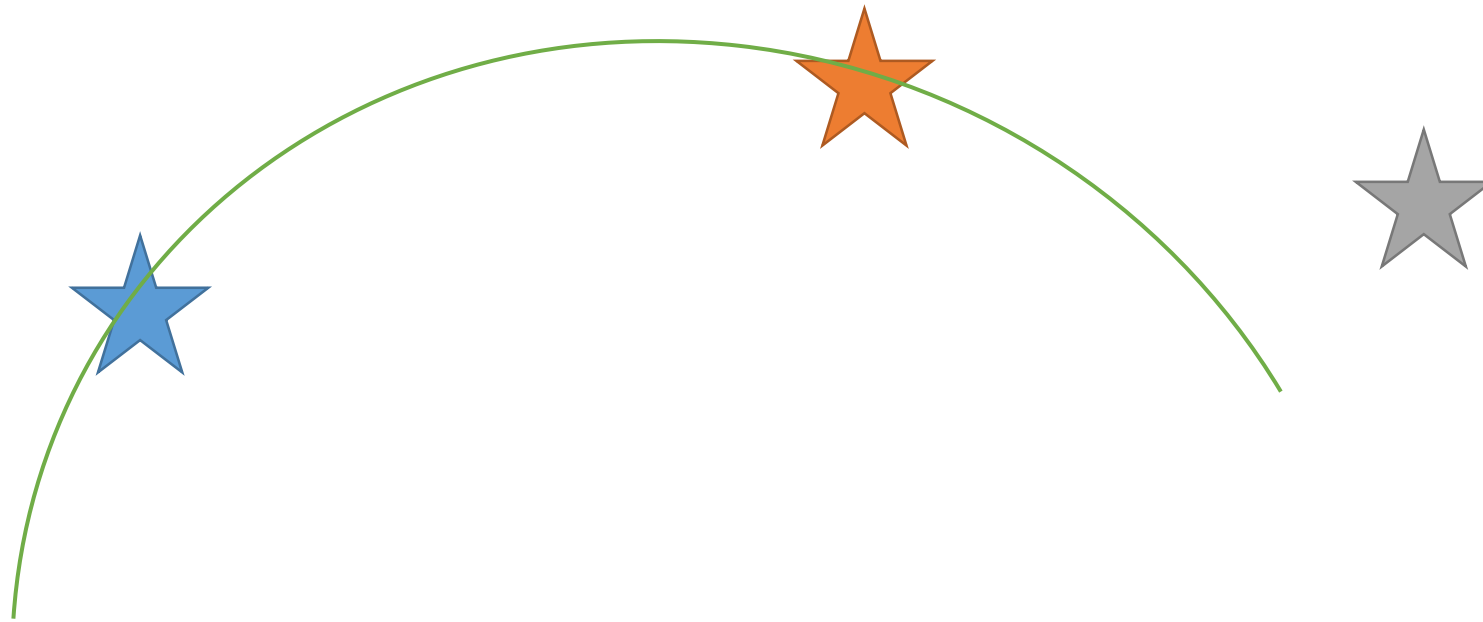


Rings of 66 hypothetical detectors (4k x 4k)

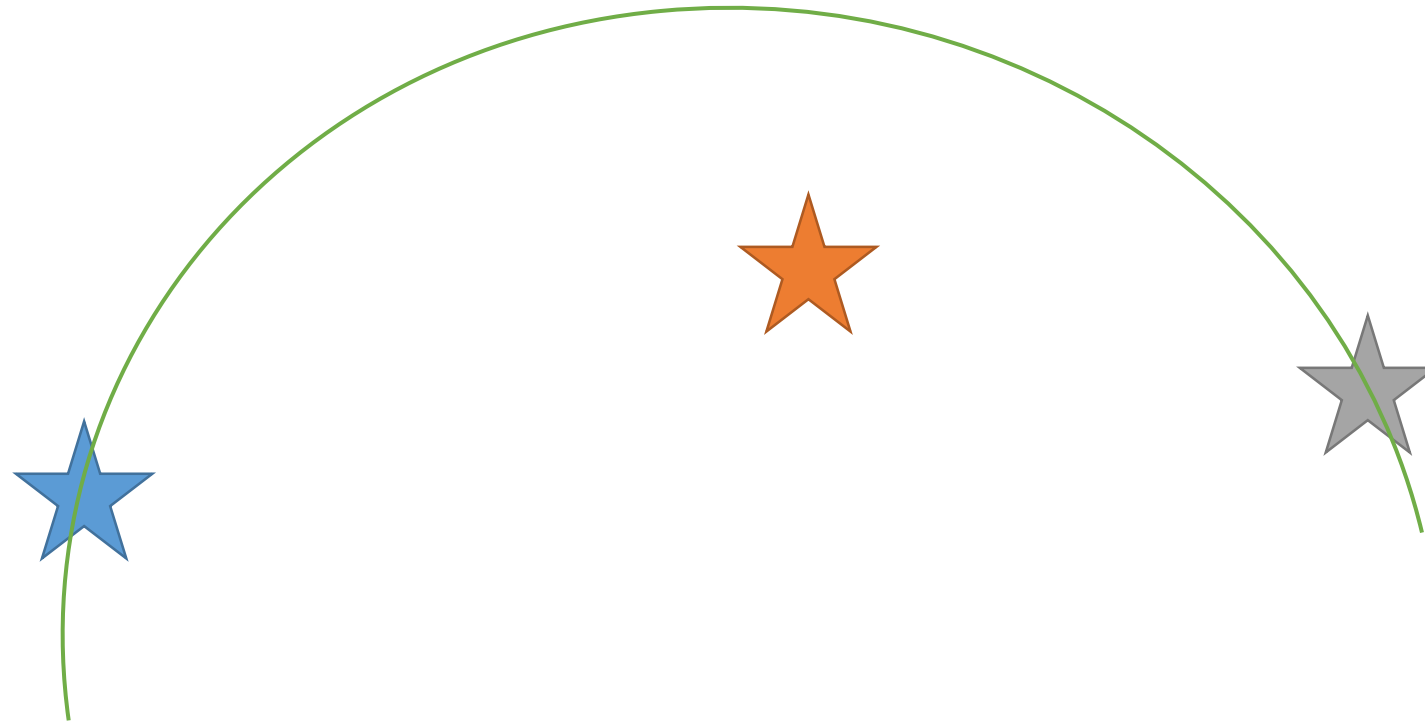
(Same number of device arranged around optical axis for comparison)



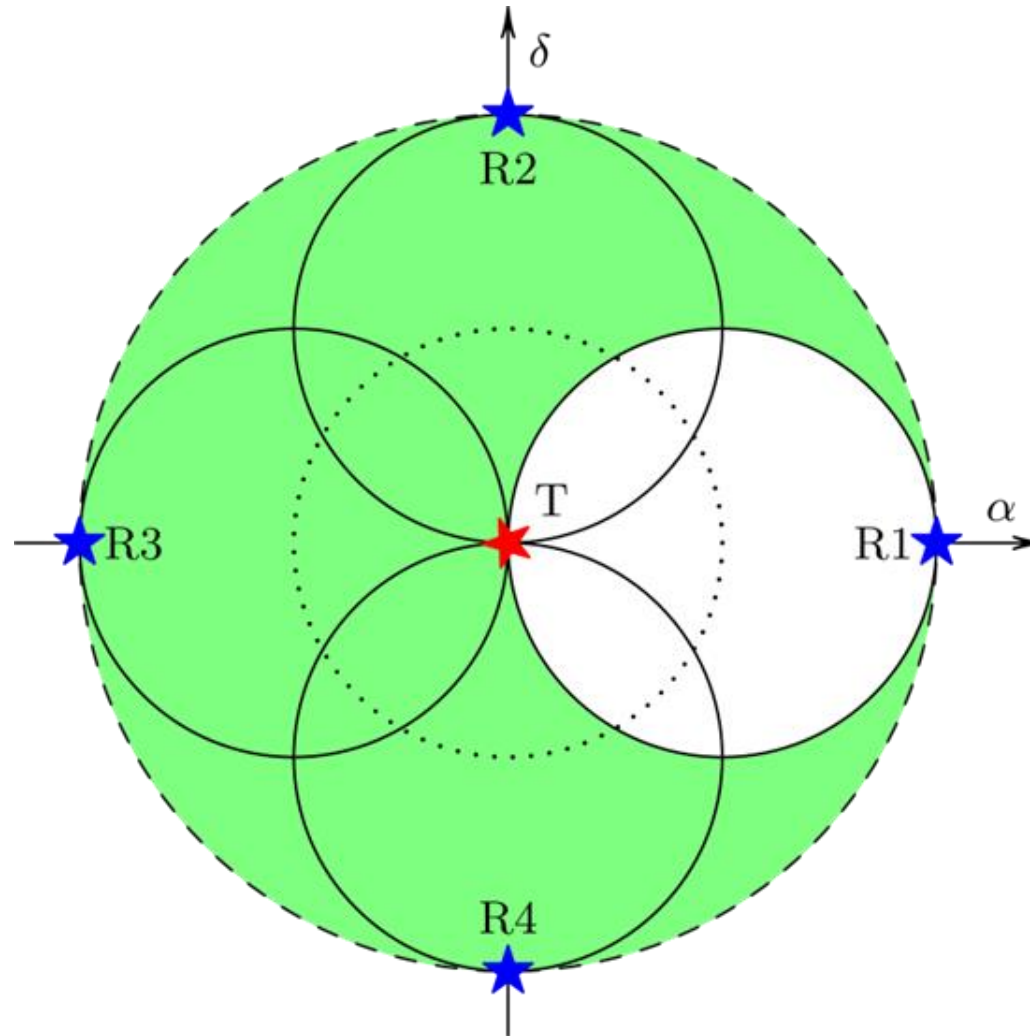
OBSERVATION STRATEGY



OBSERVATION STRATEGY



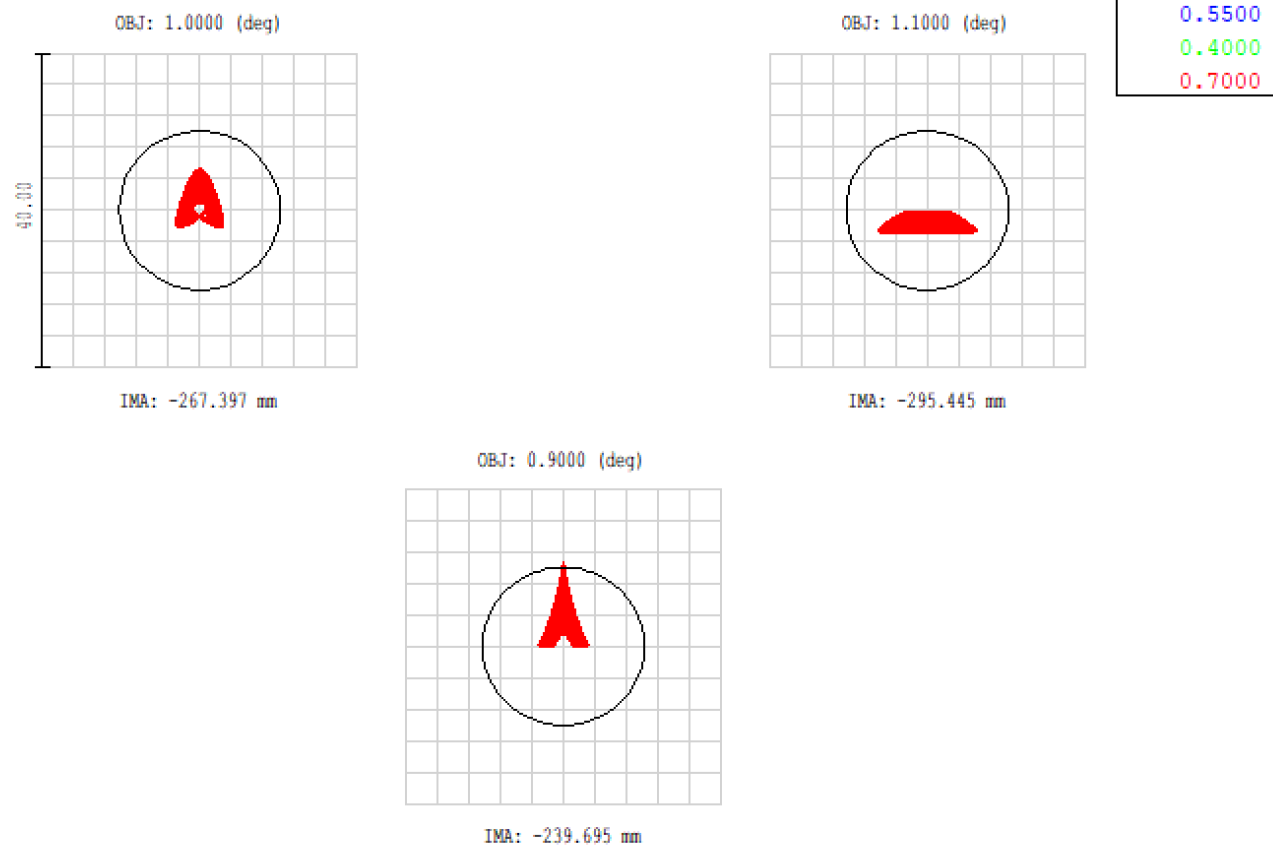
EQUIVALENT FIELD



Gai talk, this workshop



OPTICAL QUALITY : SPOT DIAGRAM



Surface: IMA

Spot Diagram

08/04/2020 Units are μm . Airy Radius: 10.06 μm

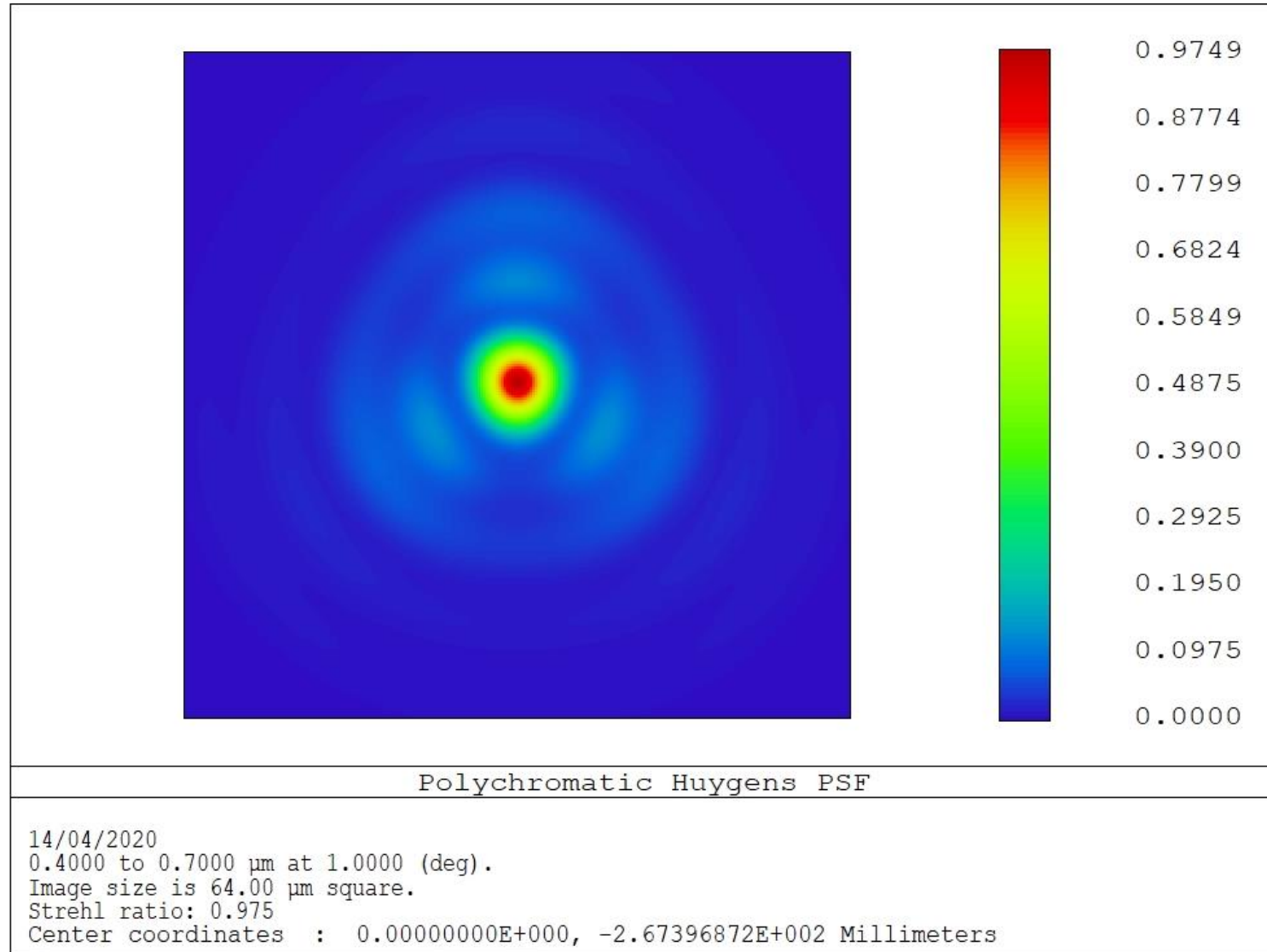
Field	: 1	2	3
RMS radius	: 1.958	4.065	3.860
GEO radius	: 5.226	6.759	10.748
Scale bar	: 40		

Reference : Chief Ray

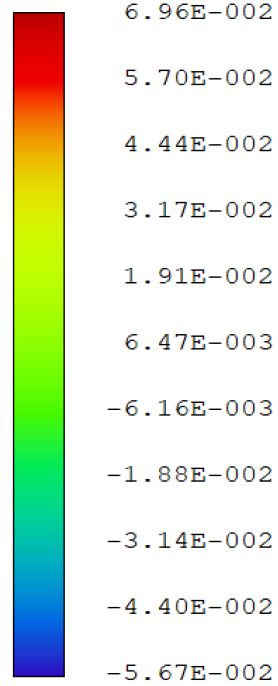
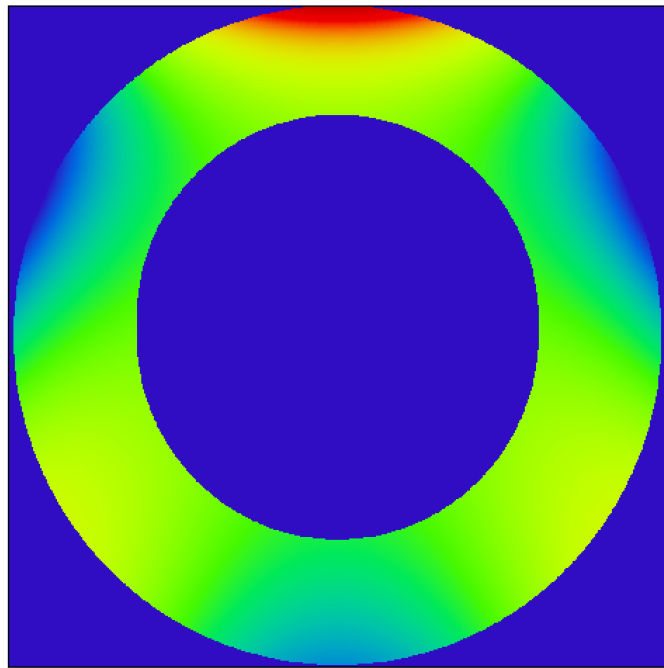
Spherical_0.5.3.ZMX
Configuration 1 of 1



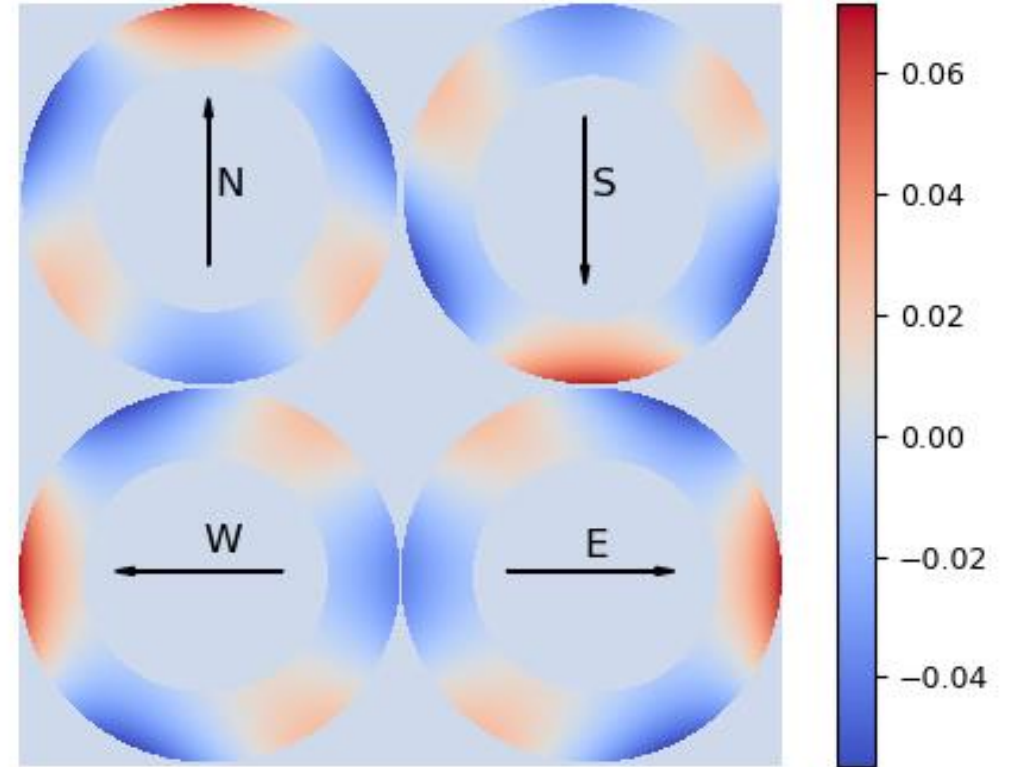
OPTICAL QUALITY: PSF



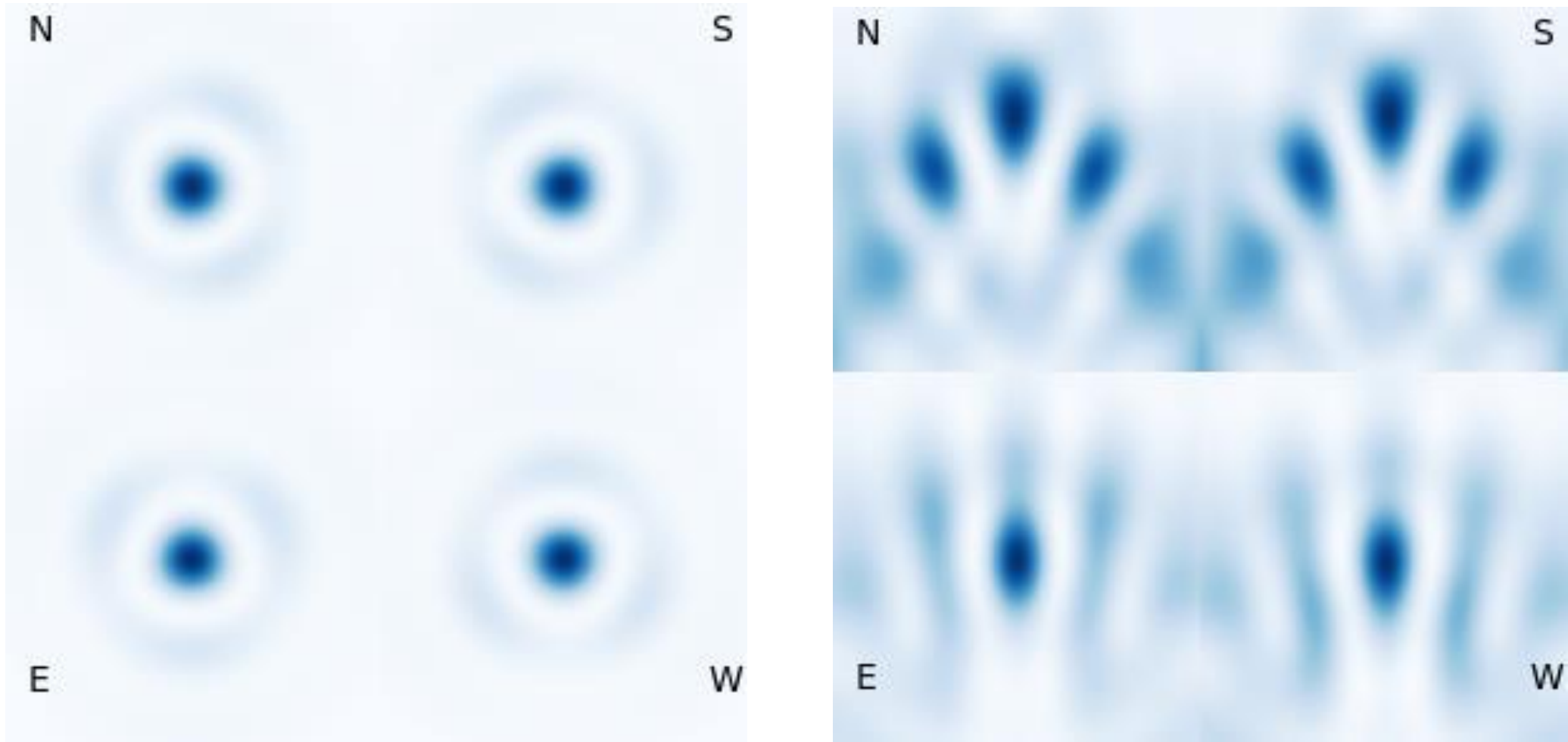
OPTICAL QUALITY: WAVEFRONT



Wavefront Function



OPTICAL QUALITY: PERTURBATIONS



PSF degradation for medium M1 tilt (1", left) and large (36", right)



MAIN POINTS FOR TRL IMPROVEMENT

1. Tolerances and sensitivity
2. Mission profile
3. Detectors
4. Thermo-mechanical analysis
5. Straylight and baffles



1. TOLERANCES

Element	Parameter	Variation	Change
M1	Tilt X and Y	+/- 3'	21.44
M2	Tilt X and Y	+/- 3'	5.48
M1	Movement X and Y	+/- 0.2 μm	2.27
M2	Movement X and Y	+/- 0.2 μm	2.24
FM	Tilt X and Y	+/- 3'	1.97
M1 - M2	Distance	+/- 0.2 μm	1.78
M3	Tilt X and Y	+/- 3'	0.47
M1	Surface irregularity	+ 0.2 Fringes	0.46
M2	Surface irregularity	- 0.2 Fringes	0.22
M1	Radius	- 1 Fringe	0.13
M2	Radius	+ 1 Fringe	0.09
M2 - FM	Distance	+ 0.2 μm	0.04
M3	Movement X and Y	+/- 0.2 μm	0.02

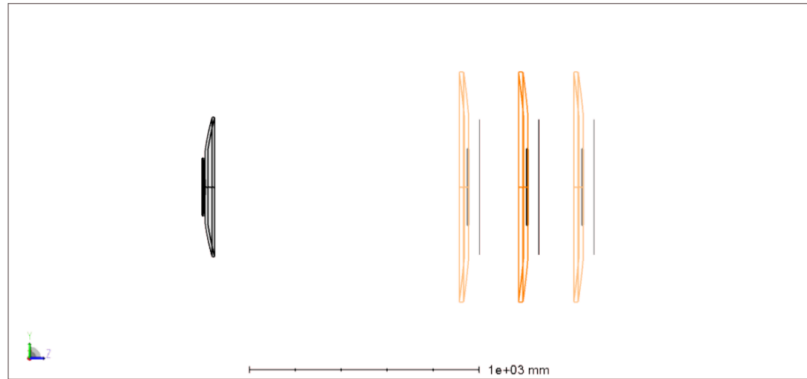
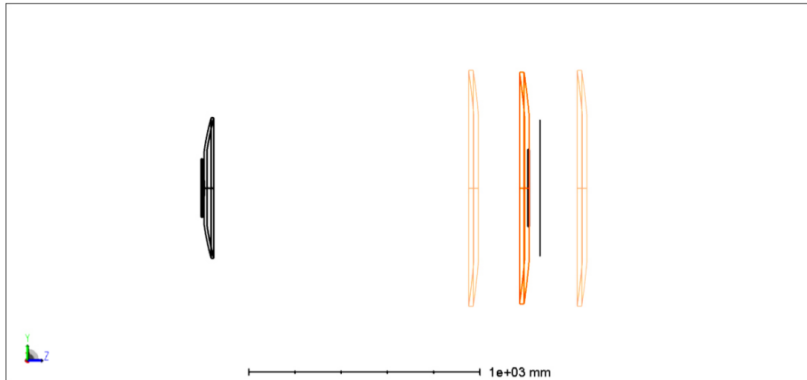


1. TOLERANCES

- Dedicated study in collaboration with Politecnico of Torino: Fornasiero, F., et. al., SPIE 2024
- Study of the two zones sensitivity and tolerances (rigid mounting of nearby components, i.e. the pairs (M1, FM) and (M2, M3) respectively)
- Definition of the experiments to increase TRL



1. TOLERANCES: TWO-ZONES



- Mechanical Hypotesis: mounting the mirrors together in 2 groups
- How does the optical allowance change?

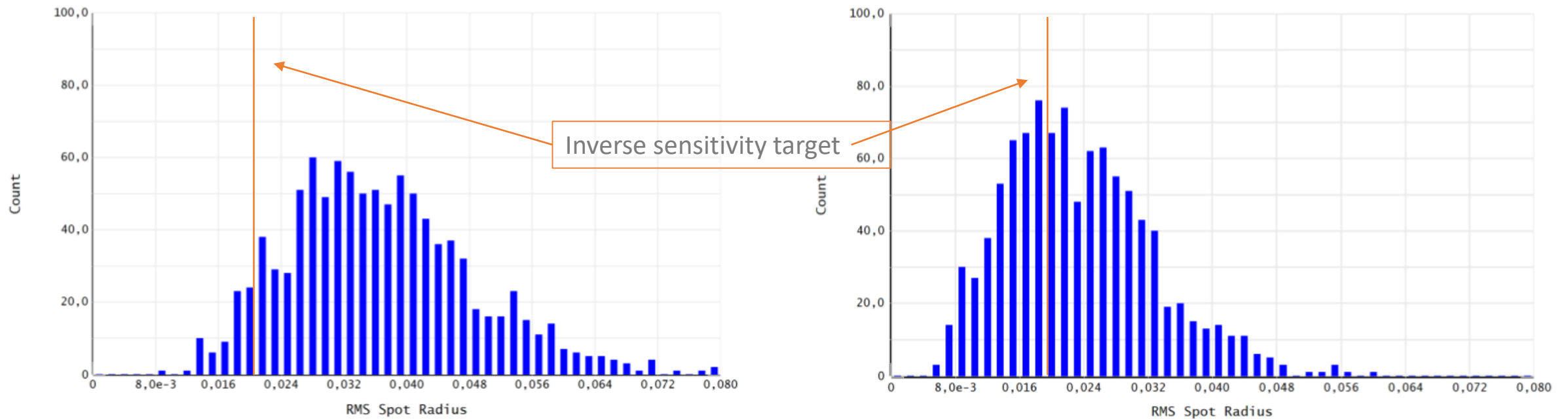
Degree Of Freedom	Only Primary Mirror Movement	Movement of the two groups
Distance	$\pm 0,011$	$\pm 0,010$
Tilt	$\pm 4,415E - 03$	$\pm 0,012$
Decentering	$\pm 0,138$	$\pm 0,137$

The tilting of the elements together seems to be compensating



1. TOLERANCES: MONTECARLO

1000 configurations, normal parameter distribution, tolerance from the inverse sensitivity

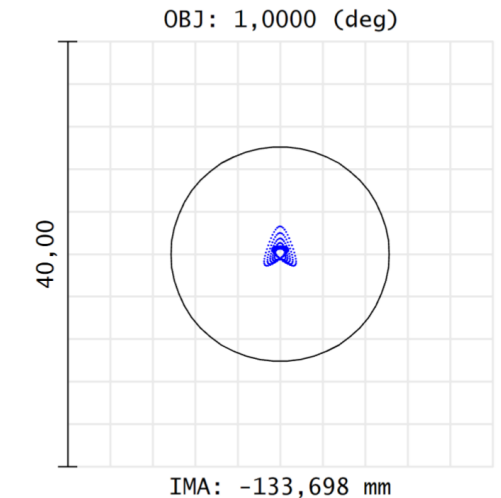
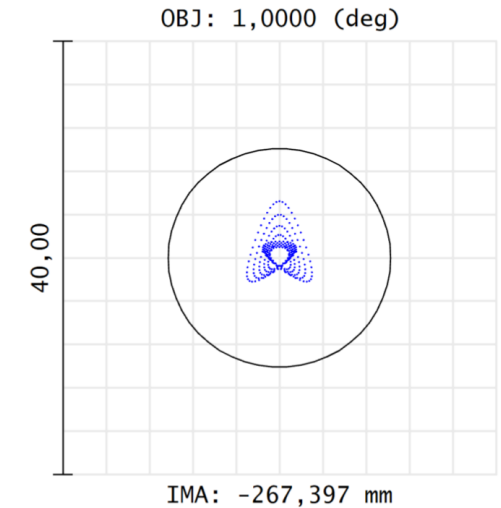


The reduction in degrees of freedoms allow for even bigger difference in real world performance



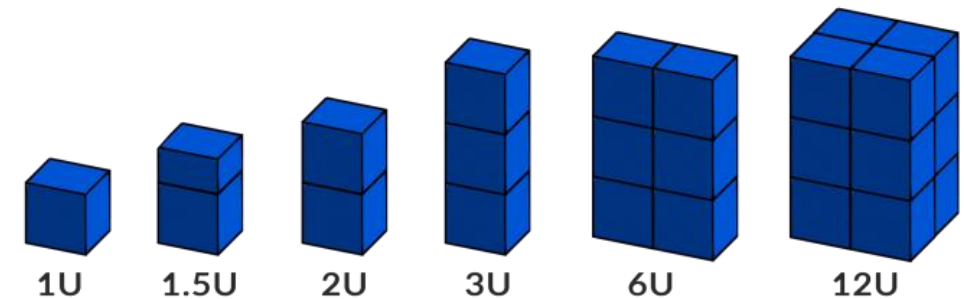
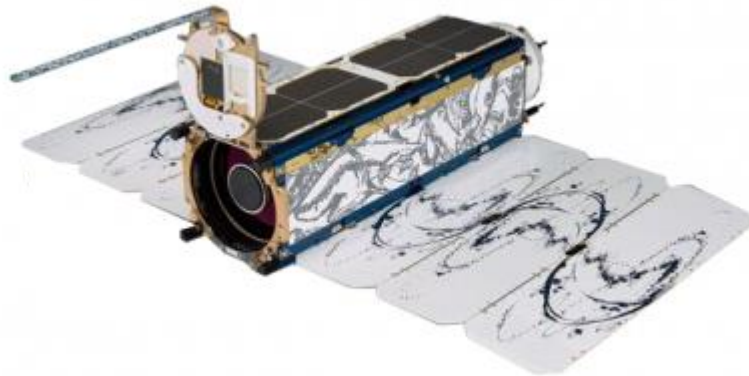
1. TOLERANCES: SCALABILITY

Degree Of Freedom	1.0 scale	0.5 scale	0.25 scale	0.2 scale	0.1 scale
Primary Mirror curvature (1/[mm])	$\pm 0,023$	$\pm 0,023$	$\pm 0,023$	$\pm 0,023$	$\pm 0,023$
Secondary Mirror curvature (1/[mm])	$\pm 0,034$	$\pm 0,035$	$\pm 0,036$	$\pm 0,035$	$\pm 0,035$
Folding Mirror curvature (fringes)	± 1	± 1	± 1	± 1	± 1
Tertiary Mirror curvature (1/[mm])	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$
Primary - Secondary distance	$\pm 0,011$	$\pm 0,011$	$\pm 0,011$	$\pm 0,011$	$\pm 0,011$
Secondary - Folding distance	$\pm 0,158$	$\pm 0,159$	$\pm 0,159$	$\pm 0,159$	$\pm 0,161$
Folding - Tertiary distance	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$
Primary Decenter	$\pm 0,138$	$\pm 0,139$	$\pm 0,141$	$\pm 0,139$	$\pm 0,142$
Primary Tilt	$\pm 4,415E - 3$	$\pm 8,879E - 03$	$\pm 0,018$	$\pm 0,022$	$\pm 0,045$
Secondary Decenter	$\pm 0,139$	$\pm 0,140$	$\pm 0,143$	$\pm 0,140$	$\pm 0,143$
Secondary Tilt	$\pm 0,014$	$\pm 0,027$	$\pm 0,066$	$\pm 0,068$	$\pm 0,164$
Folding Decenter	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$
Folding Tilt	$\pm 0,024$	$\pm 0,048$	$\pm 0,159$	$\pm 0,121$	$\pm 0,200$
Tertiary Decenter	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$
Tertiary Tilt	$\pm 0,082$	$\pm 0,164$	$\pm 0,200$	$\pm 0,200$	$\pm 0,200$
Surface Irregularity for all surfaces	$\pm 0,2$	$\pm 0,2$	$\pm 0,2$	$\pm 0,2$	$\pm 0,2$



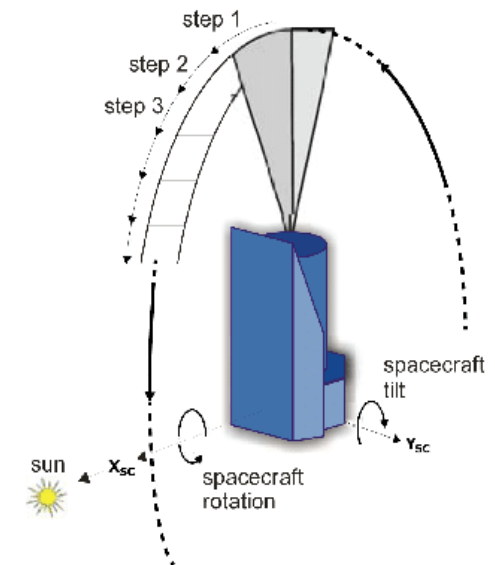
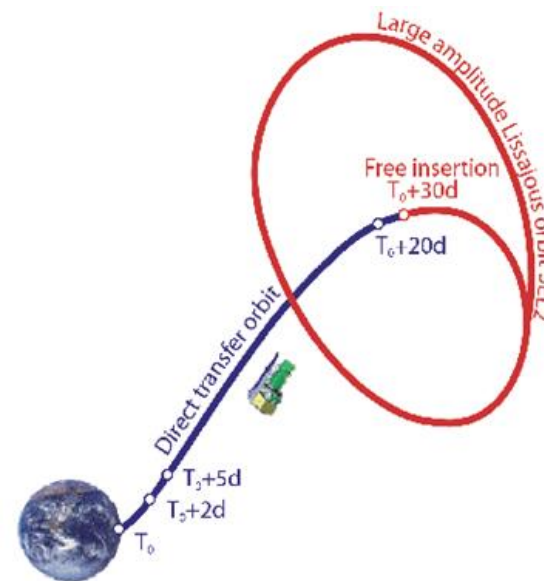
1. TOLERANCES: MINIATURIZATION

- Objective: test the TRL of the optomechanical alignment
- A 6U – 12U cubesat will be enough to prove the benefits of the optical concept



2. MISSION PROFILE

- Dedicated study in collaboration with Politecnico di Torino: Scandaglia, C., et. al., SPIE 2024
- Halo or Lissajous orbit around Lagrange point L2 of Sun-Earth system
- Observation of target stars for extended periods of time
- Cubesat mission too



2. MISSION PROFILE

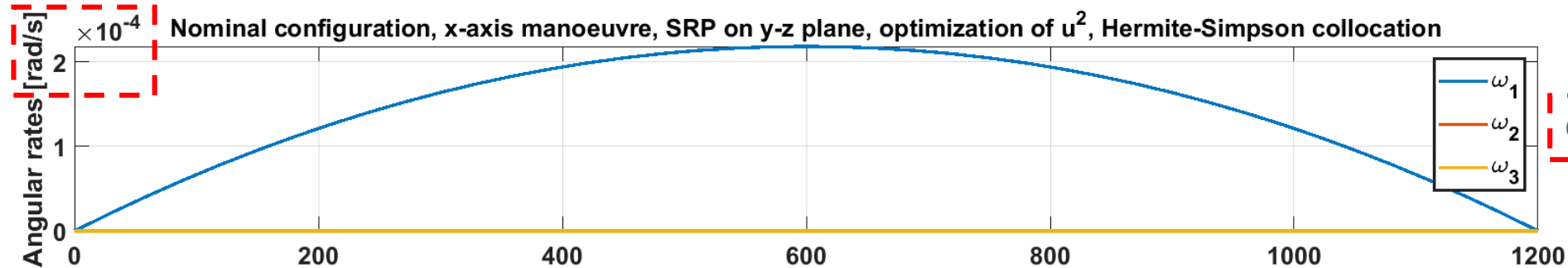
- Mathematical model update to more closely align with a real-world scenario
 - e.g. more accurate representation of solar radiation pressure contribution
- Larger number of parametrization conditions
- Use of indirect optimization methods
- Investigation of unusual behaviours
- Selection and sizing of actuating system
- Pointing stability maintenance over long periods
- We used targets within 20'; 20 min observation; 20 min of movement



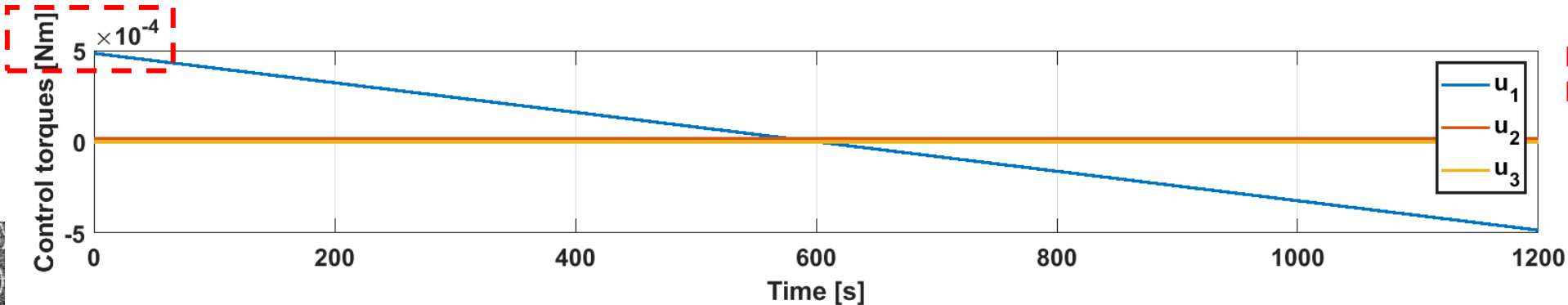
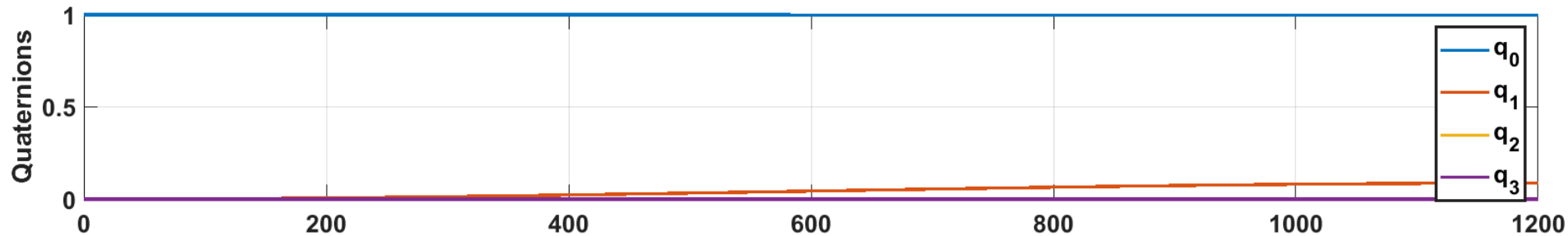
2. MISSION PROFILE

No reaction wheels, thrusters enough

$\gamma_T = 1 \text{ Nm}$



$\omega_{\max} = 2.2 \cdot 10^{-4} \text{ rad/s}$



$u_{\max} = 5 \cdot 10^{-4} \text{ Nm}$

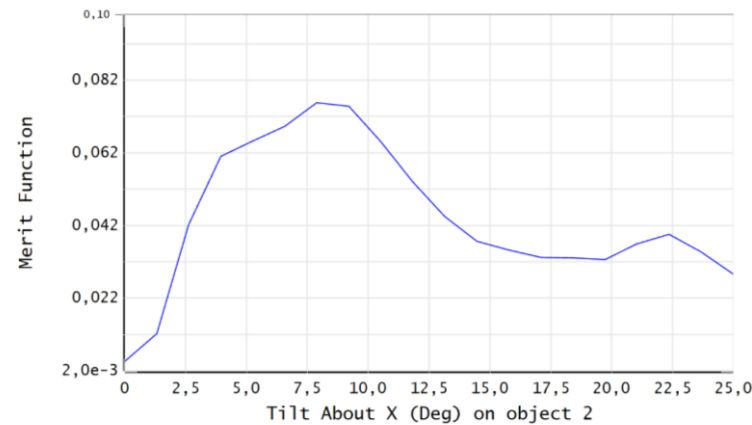
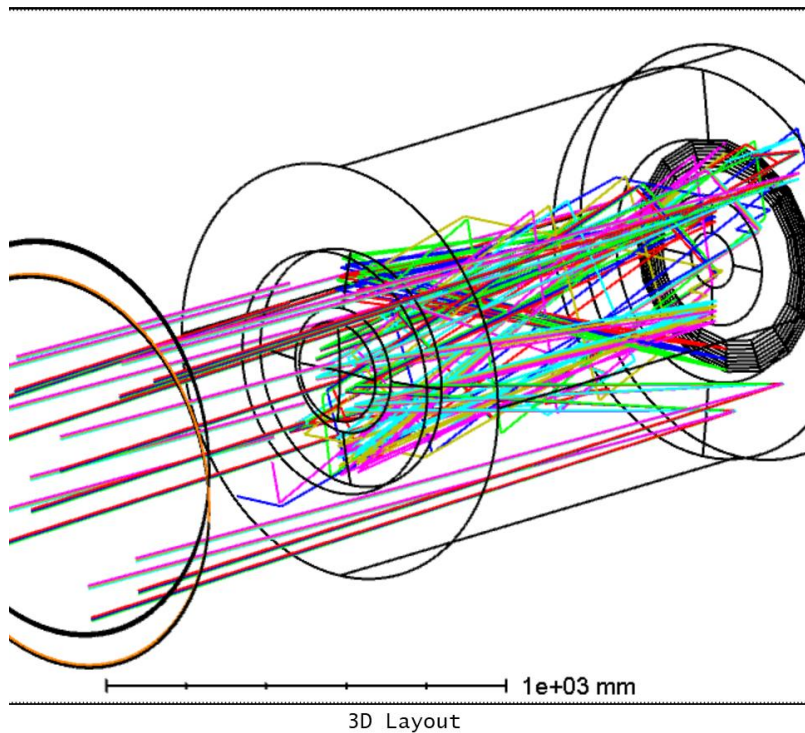


3. DETECTORS AND 4. THERMO-MECHANICAL ANALYSIS

- The proposed detector is only for illustration purposes (i.e. array of 64 4k x 4k)
- A dedicated study has been started in partnership with Arcetri and Bologna INAF Institutes
- STOP (Structural-Thermal-Optical-Performance) analysis
- Laboratory experiments and demonstration of the simplified alignment on a scaled (1:8) TMA+FPA System lab prototype.

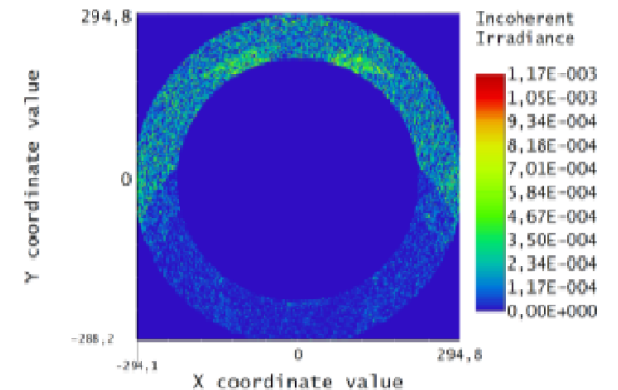
5. STRAYLIGHT AND BAFFLES

- Dedicated study and collaboration with UniFi expert group



Point Source Transmittance (PST) plot

Irradiance on the focal plane from a 7,5° source (e.g the Moon)



COLLABORATION

- INAF OATo
 - INAF Arcetri
 - INAF Bologna
 - Laboratory activities at the optics laboratory in Turin, the Space Technologies laboratory in Arcetri and the Cryowaves laboratory in Bologna.
 -
 - We welcome science/technological collaboration
- Politecnico di Torino

CONCLUSIONS

- Solid and robust experiment concept
- Good level of study
- Most of the critical issues studied or in progress
- Promising results

NEXT (PARALLEL) STEP

- Evolution of the design for further applications
- Careful focus on following presentation (Gai, M.)